

*PROM International Workshop 2022*

# A gentle introduction to **Mixture Models** - Part 2

**Prof. Salvatore Ingrassia**

*Department of Economics and Business  
University of Catania (Italy)*

*[salvatore.ingrassia@unict.it](mailto:salvatore.ingrassia@unict.it)*

*<http://www.dei.unict.it/docenti/salvatore.ingrassia>*

Cracow University of Economics  
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## 2. Mixtures of Regression Models

*"It is a capital mistake to theorize before one has data. Insensibly one begins to twist facts to suit theories, instead of theories to suit facts".*

Sherlock Holmes, *A Scandal in Bohemia*

# Outline

## 1 2.1. Mixtures of Regressions

- 2.1.1. Models with covariates
- 2.1.2. Mixture of Regressions (with fixed covariates)
- 2.1.3. Mixture Models with Concomitant Variables
- 2.1.4. Mixture of generalized linear models
- 2.1.5. Labo activity with R

## 2.1 Mixtures of Regressions

### Agenda

- Models with covariates
- Mixture of Regressions (with fixed covariates)
- Mixture Regressions with Concomitant Variables
- Mixture of generalized linear models
- Identifiability of a mixture of linear models

# Introduction

Consider a pair  $(Y, X_1, \dots, X_d)$  of a response variable  $Y$  and covariates  $(X_1, \dots, X_d)'$  defined on some population  $\Omega$  with values in  $\mathbb{R} \times \mathbb{R}^d$ .

Assume we are provided with a sample of  $N$  i.i.d. realizations of  $(Y, X_1, \dots, X_d)$  and the dependence of  $Y_n$  on  $\mathbf{x}_n$  is modeled by a multiple regression model

$$\begin{aligned} Y_n &= \beta_0 + \beta_1 x_{n1} + \dots + \beta_d x_{nd} + \varepsilon_n \\ &= \boldsymbol{\beta}' \mathbf{x}_n + \varepsilon_n \end{aligned}$$

where

- $\boldsymbol{\beta} = (\beta_0, \beta_1, \dots, \beta_d)' \in \mathbb{R}^{d+1}$  are unknown parameters,
- $\mathbf{x}_n = (1, x_{n1}, \dots, x_{nd})' \in \mathbb{R}^{d+1}$  denotes the augmented covariate vector.
- $\varepsilon_1, \dots, \varepsilon_N \sim N(0, \sigma_\varepsilon^2)$ .

## The problem

*In many circumstances, the assumption that the regression coefficients are fixed over all possible realizations of  $Y_1, \dots, Y_N$  is inadequate, and models where the regression coefficients change are of practical interest.*

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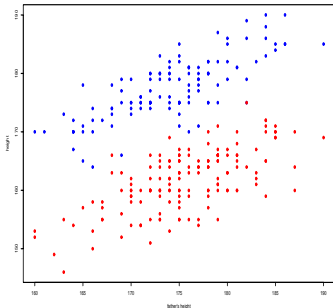
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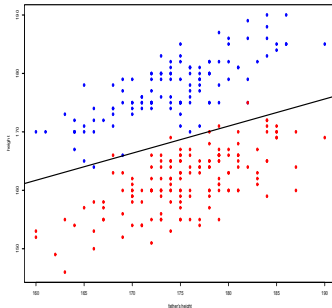
## Example A: Student Data

Data come from a survey on  $N = 270$  university students.

Consider the relationship between student height and student's father height. Two groups: males and females (blue=males, red=females).



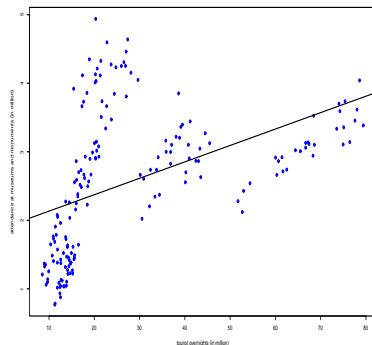
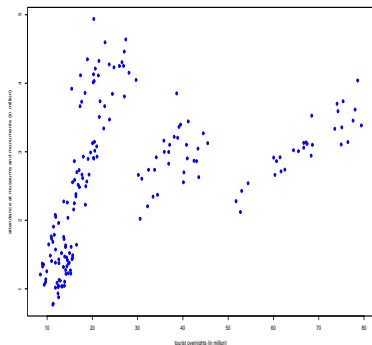
scatter plot



single linear regression model

## Example B: Tourism Data

Data concern  $N = 180$  monthly observations about the *attendance at museums and monuments* ( $Y$ , data in millions) on the *tourist overnights* ( $X$ , data in millions) in Italy over the 15-year period spanning from January 1996 to December 2010.



plot of data (*left*); *b*) single linear regression model (*right*).

## Mixture models with covariates

Consider a pair  $(Y, \mathbf{X})$  of a response variable  $Y$  and covariates  $\mathbf{X}$  defined on some heterogeneous population  $\Omega$  partitioned into  $G$  disjoint homogeneous subpopulations, i.e.  $\Omega = \Omega_1 \cup \dots \cup \Omega_G$ .

We focus on modeling the dependence between  $Y$  and  $\mathbf{X}$  based on data coming from a heterogeneous population.

In this framework, mixture models provide a flexible approach for a wide variety of random phenomena characterized by unobserved heterogeneity.

### Two first approaches

- Mixture of regression models (with fixed covariates) (MR),
- Mixture of regression models with concomitant variables (MRC)

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## Mixture of Regression Models (MR) 1/3

Dependence between  $Y$  and  $\mathbf{X}$  for data coming from a heterogeneous population can be modeled by a *finite mixture of regressions (FMR)*.

### Mixtures of Regressions (MR)

Consider a pair  $(Y, \mathbf{X})$  of a response variable  $Y$  and covariates  $\mathbf{X}$  defined on some population  $\Omega$ . We say that the distribution of  $Y|\mathbf{x}$  is a **mixture of regressions** if it has pdf given by

$$p(y|\mathbf{x}; \boldsymbol{\psi}) = \sum_{g=1}^G f(y|\mathbf{x}; \boldsymbol{\theta}_g) \pi_g .$$

where:

- $f(y|\mathbf{x}, \boldsymbol{\theta}_g)$  is the conditional density of  $Y$  given  $\mathbf{x}$  in the group  $\Omega_g$ ; the conditional densities belong to the same parametric family, indexed in  $\boldsymbol{\theta}_g \in \Theta$ ,  $g = 1, \dots, G$ .
- $\pi_g = p(\Omega_g)$  is the mixing weight of  $\Omega_g$ , ( $\pi_g > 0$  and  $\sum_{g=1}^G \pi_g = 1$ ).
- $\boldsymbol{\psi} = (\pi_1, \dots, \pi_G, \boldsymbol{\theta}'_1, \dots, \boldsymbol{\theta}'_G)' \in \Psi$  is the vector of all parameters.

## Mixture of Linear Regression Models (MR) 2/3

In the simplest case, we assume that a set of  $G$  linear regression models characterized by the parameters  $(\beta_1, \sigma_{\varepsilon,1}^2), \dots, (\beta_G, \sigma_{\varepsilon,G}^2)$  exist, and that for each observation pair  $(Y_n, \mathbf{x}_n)$  the model

$$Y_n = \beta_{0g} + \beta'_{1g} \mathbf{x}_n + \varepsilon_{n,g} \quad g = 1, \dots, G$$

where  $\beta_g = (\beta_{g0}, \beta'_{1g})' = (\beta_{g0}, \beta_{g1}, \dots, \beta_{gd})'$ ,  $\mathbf{x}_n = (x_{n1}, \dots, x_{nd})'$  and  $\varepsilon_{n,g} \sim N(0, \sigma_{\varepsilon,g}^2)$ , holds with probability  $\pi_g > 0$ .

The quantities  $\beta_1, \dots, \beta_G$  as well as  $\sigma_{\varepsilon,1}^2, \dots, \sigma_{\varepsilon,G}^2$  are unknown parameters that need to be estimated from the data.

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## Mixture of Linear Regression Models (MR) 3/3

Let us set  $\tilde{\mathbf{x}} = (1, \mathbf{x}')'$  and then  $\beta'_g \tilde{\mathbf{x}}_n = \beta_{0g} + \beta'_{1g} \mathbf{x}_n$ .

Then, the conditional density of  $Y$  given the observation  $\mathbf{x}_n$ , can be written as

$$p(y|\mathbf{x}_n; \boldsymbol{\psi}) = \sum_{g=1}^G \phi(y; \beta'_g \tilde{\mathbf{x}}_n, \sigma_{\varepsilon,g}^2) \pi_g, \quad \pi_g \geq 0, \quad \sum_{g=1}^G \pi_g = 1$$

where the vector  $\boldsymbol{\psi}$  denotes the overall parameters of the model.

For each value of  $\mathbf{x}_n$ , the conditional distribution of  $Y_n$  given  $\mathbf{x}_n$  is a mixture of univariate normal distributions with mean  $\mu_{ng} = \beta'_g \tilde{\mathbf{x}}_n$  and variance  $\sigma_{\varepsilon,g}^2$ .

This model is also called *latent class regression* or *clusterwise regression*.

### Remark

A finite mixture of regression models may be seen as an extension of a mixture of univariate normal distributions where the mean in the mixture distribution depends on explanatory variables.

On the other hand, a finite mixture of univariate normal distributions may be seen as that special case of finite mixtures of regression models where  $\mu_{ng} = \beta_{g0}$  and  $\beta_g = \mathbf{0}$ .

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# Mixture of Regressions with Concomitant (MRC)

Extension of MR is the *mixture of regressions with concomitant variables (MRC)*.

## Mixtures of Regressions with Concomitant (MRC)

Consider a pair  $(Y, \mathbf{X})$  of a response variable  $Y$  and covariates  $\mathbf{X}$  defined on some population  $\Omega$ . We say that the distribution of  $Y|x$  is a **mixture of regressions** if has pdf given by

$$p(y|\mathbf{x}, \boldsymbol{\psi}) = \sum_{g=1}^G f(y|\mathbf{x}; \boldsymbol{\theta}_g) p(\Omega_g|\mathbf{x}, \mathbf{w}).$$

## Mixture of Regressions with Concomitant (MRC)

The mixing weights  $p(\Omega_g|\mathbf{x}, \mathbf{w})$  are now functions depending on  $\mathbf{x}$  through some parameters  $\mathbf{w}$ , and  $\psi = (\pi_1, \dots, \pi_G, \boldsymbol{\theta}_1, \dots, \boldsymbol{\theta}_G, \mathbf{w})$ .

$p(\Omega_g|\mathbf{x}, \mathbf{w})$  is usually modeled by a multinomial logistic distribution with the first component as baseline, that is:

$$p(\Omega_g|\mathbf{x}, \mathbf{w}) = \frac{\exp(\mathbf{w}'_g \mathbf{x})}{\sum_{h=1}^G \exp(\mathbf{w}'_h \mathbf{x})}.$$

where  $\mathbf{w}_g = (w_{g0}, w_{g1}, \dots, w_{gd})' \in \mathbb{R}^{d+1}$  and  $\mathbf{w} = (\mathbf{w}'_1, \dots, \mathbf{w}'_G)' \in \mathbb{R}^{G(d+1)}$ .

# The EM algorithm for mixtures of simple regression

## 1/2

For simplicity, we present only the case of mixtures of simple regression models:

$$p(x; \boldsymbol{\psi}) = \pi_1 \phi(y; \beta_{10} + \beta_{11}x, \sigma_1^2) + \cdots + \pi_G \phi(y; \beta_{G0} + \beta_{G1}x, \sigma_G^2)$$

Let  $\mathbf{x} = (x_1, \dots, x_N)'$  be a sample taken from  $p(x; \boldsymbol{\psi})$ , the complete log-likelihood function is given by

$$\mathcal{L}_c(\boldsymbol{\psi}) = \sum_{n=1}^N \sum_{g=1}^G z_{ng} \log \pi_g + \sum_{n=1}^N \sum_{g=1}^G z_{ng} \log \phi(y_n; \beta_{g0} + \beta_{g1}x_n, \sigma_g^2),$$

where the vectors  $\mathbf{z}_1, \dots, \mathbf{z}_N$  are the missing data which are realizations of the random vectors  $\mathbf{Z}_1, \dots, \mathbf{Z}_N$ , where  $Z_{ng} = (\mathbf{Z}_n)_g$ , is defined as  $Z_{ng} = 1$  if  $x_n$  comes from  $\Omega_g$  and  $Z_{ng} = 0$  otherwise, for  $n = 1, \dots, N$  and  $g = 1, \dots, G$ .

# The EM algorithm for mixtures of simple regression 2/2

We get the following estimates at step  $r$ :

$$\tau_{ng}^{(r+1)} = \tau_{ng}(\mathbf{x}; \boldsymbol{\psi}^{(r)}) = \frac{\pi_g^{(r)} \phi(x_n; \beta_{g0}^{(r)}, \beta_{g1}^{(r)}, \sigma_g^{2(r)})}{p(x_n; \boldsymbol{\psi}^{(r)})}$$

$$\pi_g^{(r+1)} = \frac{1}{N} \sum_{n=1}^N \tau_{ng}^{(r+1)}$$

$$\beta_{g1}^{(r+1)} = \frac{\sum_{n=1}^N \tau_{ng}^{(r+1)} (y_n - \bar{y}_g)(x_n - \bar{x}_g)}{\sum_{n=1}^N \tau_{ng}^{(r+1)} (x_n - \bar{x}_g)^2}$$

$$\beta_{g0}^{(r+1)} = \bar{y}_g - \beta_{g1}^{(r+1)} \bar{x}_g$$

$$(\sigma_g^2)^{(r+1)} = \frac{\sum_{n=1}^N \tau_{ng}^{(r+1)} (y_n - \beta_{g0}^{(r+1)} - \beta_{g1}^{(r+1)} x_n)^2}{\sum_{n=1}^N \tau_{ng}^{(r+1)}}$$

# Parameter estimation and classification

Assume we are provided with a set of  $N$  independent observation pairs  $\{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)\}$  drawn from a mixture of regressions (MR/MRC). Then:

- 1 for fixed  $G$ , estimate model parameters, usually according to the maximum likelihood approach, using the EM algorithm;
- 2 if  $G$  is unknown, then
  - 1 repeat step 1 for different number  $G$  of groups;
  - 2 select  $G$  according to model selection criteria like BIC or ICL;
- 3 based on the estimate  $\hat{\psi}$ , compute the posterior probability  $\tau_g(\mathbf{x}_n, y_n; \hat{\psi})$  that the  $n$ th unit  $(y_n, \mathbf{x}_n)$  belong to the  $g$ th group  $\Omega_g$ :

$$\text{MR : } \tau_g(\mathbf{x}_n, y_n | \hat{\psi}) = \frac{f(y_n | \mathbf{x}_n, \hat{\theta}_g) \hat{\pi}_g}{p(y_n | \mathbf{x}; \hat{\psi})} = \frac{f(y_n | \mathbf{x}_n; \hat{\theta}_g) \hat{\pi}_g}{\sum_{h=1}^G f(y_n | \mathbf{x}_n, \hat{\theta}_h) \hat{\pi}_h}$$

$$\text{MRC : } \tau_g(\mathbf{x}_n, y_n | \hat{\psi}) = \frac{f(y_n | \mathbf{x}_n, \hat{\theta}_g) p(\Omega_g | \mathbf{x}_n, \hat{\mathbf{w}})}{p(y | \mathbf{x}; \hat{\psi})} = \frac{f(y_n | \mathbf{x}_n, \hat{\theta}_g) \exp(\mathbf{w}'_g \mathbf{x}_n)}{\sum_{h=1}^G f(y_n | \mathbf{x}_n, \hat{\theta}_h) \exp(\mathbf{w}'_h \mathbf{x}_n)}$$

and classify units into groups according to the maximum a posteriori probability (MAP) criterion.

# Model selection

## The problem

*How to estimate the number  $G$  of groups?*

- For model selection, usually BIC and ICL.

<i>Criterion</i>	<i>Definition</i>
BIC	$= -2\mathcal{L}(\psi) + K \log N$
ICL	$\approx \text{BIC} + \sum_n 1_{\hat{z}_{ig}} \ln \hat{z}_{ig}$

are usually adopted, where  $K$  is the number of parameter in the model.

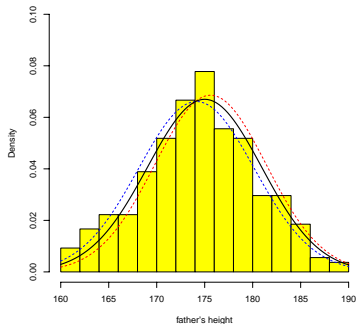
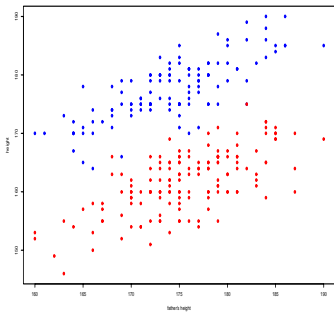
## Note

*There may be no particular reasons for choosing a single best model over the other ones. On the contrary, it makes more sense to "deselect" models that are obviously poor, maintaining a subset for further considerations.*

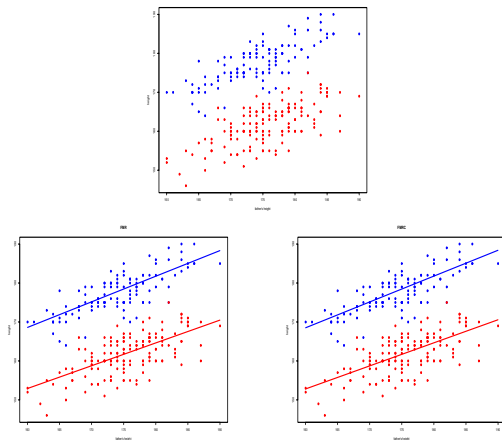
## Example A: Student data (cont'd) 2/4

The relationship between *height of the respondent* and *height of respondent's father* has been modeled according to both finite mixture of regression (MR) and finite mixture of regression with concomitant (MRC).

The histogram of the  $X$ -variable *height of respondent's father* does not show any cluster structure along the  $X$ -variable.



## Example A: Student data (cont'd) 3/4



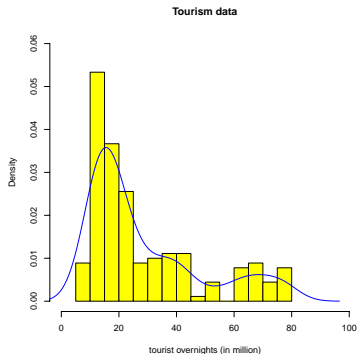
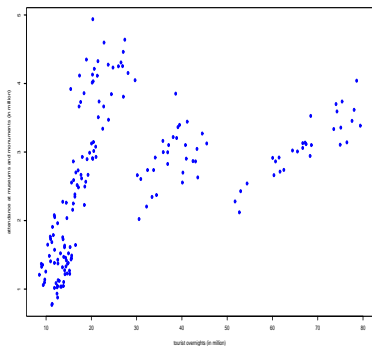
The two models give in practice the same results

## Example A: Student data (cont'd) 4/4

	MR	MRC																								
<i>Confusion Matrices</i>	<table border="1"> <thead> <tr> <th></th> <th colspan="2"><i>Predicted</i></th> </tr> <tr> <th><i>Actual</i></th> <th><i>M</i></th> <th><i>F</i></th> </tr> </thead> <tbody> <tr> <th><i>M</i></th> <td>112</td> <td>7</td> </tr> <tr> <th><i>F</i></th> <td>0</td> <td>151</td> </tr> </tbody> </table>		<i>Predicted</i>		<i>Actual</i>	<i>M</i>	<i>F</i>	<i>M</i>	112	7	<i>F</i>	0	151	<table border="1"> <thead> <tr> <th></th> <th colspan="2"><i>Predicted</i></th> </tr> <tr> <th><i>Actual</i></th> <th><i>M</i></th> <th><i>F</i></th> </tr> </thead> <tbody> <tr> <th><i>M</i></th> <td>113</td> <td>6</td> </tr> <tr> <th><i>F</i></th> <td>0</td> <td>151</td> </tr> </tbody> </table>		<i>Predicted</i>		<i>Actual</i>	<i>M</i>	<i>F</i>	<i>M</i>	113	6	<i>F</i>	0	151
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<i>Misclassification Error</i>	2.59%	2.22%																								
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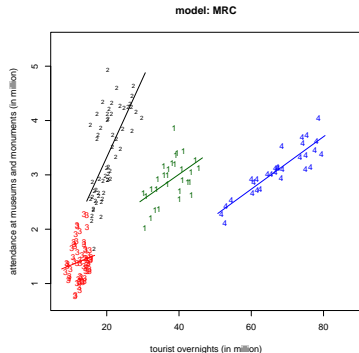
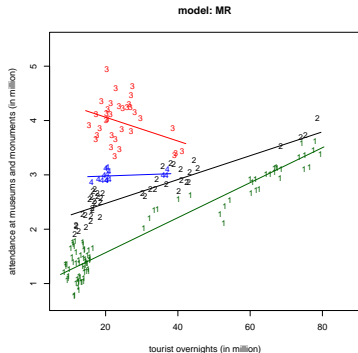
## Example B: Tourism data (cont'd - 2/4)

Cluster structure with respect to the covariate:



The data have been modeled without considering the time information (month labels)

## Example B: Tourism data (cont'd - 3/4)



- choice:  $G = 4$  for economic reasons.

## Example B: Tourism data (cont'd - 4/4)

Model: *Mixture of Regressions with Concomitant (FMRC)*.

Group	Month											
	Jan	Feb	Mar	Apr	May	Jun	Jul	Aug	Sep	Oct	Nov	Dec
	1	2	3	4	5	6	7	8	9	10	11	12
1	0	0	0	0	0	15	0	0	15	0	0	0
2	0	1	12	15	15	0	0	0	0	15	0	0
3	15	14	3	0	0	0	0	0	0	0	15	15
4	0	0	0	0	0	0	15	15	0	0	0	0

The four groups identify almost perfectly the units from time point of view.

Group 1 : units in June and September (early and late summer);

Group 2 : units in March, April, May and October (spring and early autumn);

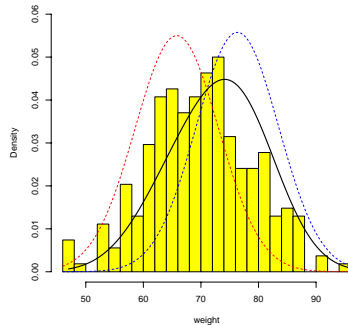
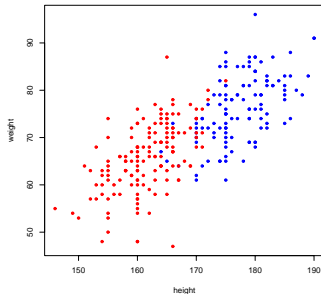
Group 3 : units from November to February (late autumn and winter);

Group 4 : units in July and August (summer);

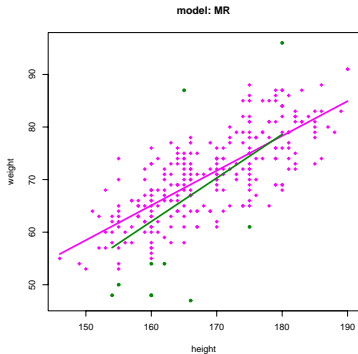
misclassification error:  $\delta = 2.22\%$

## Example C: Student data 2 (cont'd) 1/2

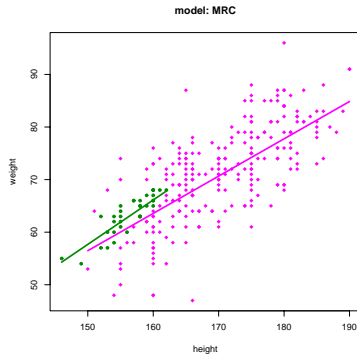
In *Student Data* consider the relationship between weight and height. Two groups: males and females (blue=males, red=females) .



## Example C: Student data 2 (cont'd) 2/2



$$\delta = 46.30\%$$
$$\text{ARI} = 0.0072$$



$$\delta = 42.96\%$$
$$\text{ARI} = 0.0105$$

### Question

*Can we do better?*

## Mixture of generalized linear models 1/3

More in general, consider mixture models of the distributions of  $Y|\mathbf{x}, \Omega_g$  taking the form

$$p(y|\mathbf{x}; \boldsymbol{\psi}) = \sum_{g=1}^G f(y|\mathbf{x}; \boldsymbol{\theta}_g) \pi_g, \quad \text{with } \pi_g \geq 0, \quad \sum_{g=1}^G \pi_g = 1$$

where  $Y$  is a dependent variable taking values in some space  $\mathcal{Y} \subseteq \mathbb{R}$  with conditional density  $p$ ,  $\mathbf{x}$  is a vector of independent variables,  $\pi_g$  is the prior probability of component  $g$ ,  $\boldsymbol{\theta}_g \in \Theta$  is the component specific parameter for the density  $f$  and  $\boldsymbol{\psi} = (\pi_1, \dots, \pi_G, \boldsymbol{\theta}'_1, \dots, \boldsymbol{\theta}'_G)' \in \Psi$  is the vector of all parameters.

In order to deal with various response types, we assume that, for each mixture component, the conditional distributions  $f(y|\mathbf{x}; \boldsymbol{\theta}_g)$  belong to the exponential family.

This yields the *mixture of generalized linear models* known as *GLIMMIX* models in the marketing literature:

$$p(y|\mathbf{x}; \boldsymbol{\psi}) = \sum_{g=1}^G f(y|\mathbf{x}; \boldsymbol{\beta}_g, \lambda_g) \pi_g, \quad \mathbf{x} \in \mathbb{R}^{d+1}, y \in \mathcal{Y}.$$

## Mixture of generalized linear models 2/3

### The binomial response.

Assume that  $Y$  takes values in  $\mathcal{Y} = \{0, 1, \dots, M\}$ , for some  $M \in \mathbb{N}$ , and that the probability mass function of  $Y|\mathbf{x}, \Omega_g$  is binomial with parameters  $(M, \mu_g(\mathbf{x}; \boldsymbol{\beta}_g)/M)$ , that is  $Y|\mathbf{x}, \Omega_g \sim \text{Bin}(M, \mu_g(\mathbf{x}; \boldsymbol{\beta}_g)/M)$ . In this case

$$f(y|\mathbf{x}; M, \boldsymbol{\beta}_g) = \binom{M}{y} \left[ \frac{\mu_g(\mathbf{x}; \boldsymbol{\beta}_g)}{M} \right]^y \left[ 1 - \frac{\mu_g(\mathbf{x}; \boldsymbol{\beta}_g)}{M} \right]^{M-y},$$

where

$$\mu_g(\mathbf{x}; \boldsymbol{\beta}_g) = M \frac{\exp(\boldsymbol{\beta}'_g \tilde{\mathbf{x}})}{1 + \exp(\boldsymbol{\beta}'_g \tilde{\mathbf{x}})}.$$

## Mixture of generalized linear models 3/3

### The Poisson response.

Assume that  $Y$  takes values in  $\mathcal{Y} = \mathbb{N}$  and that the probability mass function of  $Y|\mathbf{x}, \Omega_g$  is Poisson with parameter  $\mu_g$ , that is  $Y|\mathbf{x}, \Omega_g \sim \text{Poi}(\mu_g(\mathbf{x}; \boldsymbol{\beta}_g))$ . In this case

$$f(y|\mathbf{x}; \boldsymbol{\beta}_g) = \exp[-\mu_g(\mathbf{x}; \boldsymbol{\beta}_g)] \frac{[\mu_g(\mathbf{x}; \boldsymbol{\beta}_g)]^y}{y!},$$

where

$$\mu_g(\mathbf{x}; \boldsymbol{\beta}_g) = \exp(\boldsymbol{\beta}_g' \tilde{\mathbf{x}}).$$

# Algorithms and software

## **flexmix: Flexible Mixture Modeling**

A general framework for finite mixtures of regression models using the EM algorithm is implemented. The E-step and all data handling are provided, while the M-step can be supplied by the user to easily define new models. Existing drivers implement mixtures of standard linear models, generalized linear models and model-based clustering.





Version: 2.3-17

Depends: R ( $\geq 2.15.0$ ), [lattice](#)

Imports: graphics, grid, grDevices, methods, [modeltools](#) ( $\geq 0.2-16$ ), [nnet](#), stats, stats4, utils

Suggests: [actuar](#), [codetools](#), [diptest](#), [Ecdat](#), [ellipse](#), [gclus](#), [glmnet](#), [lme4](#) ( $\geq 1.1$ ), [MASS](#), [mgcv](#) ( $\geq 1.8-0$ ), [mlbench](#), [multcomp](#), [mvtnorm](#), [SuppDists](#), [survival](#)

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Author: Bettina Gruen  [aut, cre], Friedrich Leisch  [aut], Deepayan Sarkar  [ctb], Frederic Mortier [ctb], Nicolas Picard  [ctb]

Maintainer: Bettina Gruen <Bettina.Gruen@R-project.org>

License: [GPL-2](#) | [GPL-3](#) [expanded from: GPL ( $\geq 2$ )]

NeedsCompilation: no

Citation: [flexmix citation info](#)

Materials: [NEWS](#)

In views: [Cluster](#), [Environmetrics](#), [Psychometrics](#)

CRAN checks: [flexmix results](#)

# Labo activity with R

**Lab\_activity\_MM\_2.R**